1. Setting of wifi and wave
2. Ipv4 using in broadcast
3. Instead of mac address, broadcast using ip address
4. Begin broadcast when create the platoon
5. Makeboundcallback:

When vehicle receive packet make the vehicle number and time callback to MATLAB

1. Schedule\_split\_event->setposition\_next\_initial->setposition\_next
2. Receivepacket socket->recv()

Q:

1. Why two callback function
2. Why 150s all vehicles stop moving(know) and 250s+ moving faster
3. Use packet size to separate or all commands use ip socket